

Control and Inverse Problems for Networks of Vibrating Strings with Attached Masses

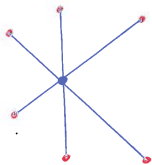
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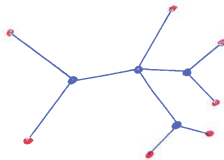
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The talk is based in part on joint work with
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and Julian Edward (Florida International University)

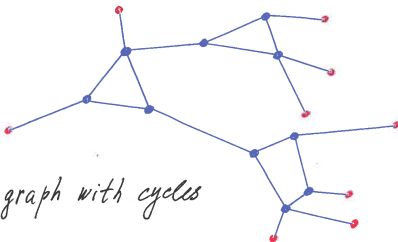
Differential Equations on Graphs



A star graph



A tree



A graph with cycles

One Interval

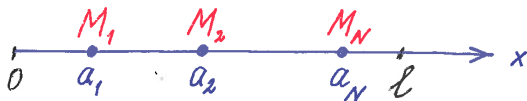
$$\rho(x) \frac{\partial^2 u}{\partial t^2} - \frac{\partial^2 u}{\partial x^2} = 0, \quad \rho \in \text{piecewise } C^2[0, \ell],$$

$$t \in (0, T), \quad x \in \Omega := (0, a_1) \cup (a_1, a_2) \cup \dots \cup (a_N, \ell),$$

$$u(a_j^-, t) = u(a_j^+, t), \quad M_j u_{tt}(a_j, t) = u_x(a_j^+, t) - u_x(a_j^-, t),$$

$$u(x, 0) = u_t(x, 0) = 0,$$

$$u(0, t) = f(t), \quad u(\ell, t) = 0.$$



$$\frac{\partial^2 u}{\partial t^2} - \frac{\partial^2 u}{\partial x^2} + q(x)u = 0, \quad t \in (0, T), \quad x \in \Omega, \quad q \in C[0, \ell].$$

$$u(x, 0) = u_t(x, 0) = 0,$$

$$u(a_j^-, t) = u(a_j^+, t), \quad M_j u_{tt}(a_j, t) = u_x(a_j^+, t) - u_x(a_j^-, t),$$

$$u(0, t) = f(t), \quad u(\ell, t) = 0.$$

Theorem 1. Let $T > 2\ell$ for $N \geq 2$ and $T \geq 2\ell$ for $N = 1$;

$$y \in W_0 := L^2(0, a_1) \times H^1(a_1, a_2) \times \cdots \times H^N(a_N, \ell),$$

$$z \in W_{-1} := H^{-1}(0, a_1) \times L^2(a_1, a_2) \times \cdots \times H^{N-1}(a_N, \ell),$$

$$y(a_j^-) = y(a_j^+), \quad j \geq 2,$$

$$y'(a_j^-) = y'(a_j^+) - M_j[y_{xx}(a_j^+) - q(a)y(a_j^+)], \quad j \geq 3, \quad y(\ell^-) = 0,$$

$$z(a_j^-) = z(a_j^+), \quad j \geq 3,$$

$$z'(a_j^-) = z'(a_j^+) - M_j[z_{xx}(a_j^+) - q(a)z(a^+)], \quad j \geq 4, \quad z(\ell^-) = 0.$$

There exists

$$f \in L^2(0, T), \quad \|f\|_{L^2(0, T)}^2 \asymp \|y\|_{W_0}^2 + \|z\|_{W_{-1}}^2,$$

such that

$$u^f(x, T) = y(x), \quad u_t^f(x, T) = z(x), \quad x \in \Omega.$$

For $N = 1$ and constant $\rho(x)$: S. Hansen and E. Zuazua (1995).

$$\begin{aligned}
 & -\varphi''(x, \lambda) + q(x)\varphi(x, \lambda) = \lambda^2\varphi(x, \lambda), \\
 & x \in \Omega := (0, a_1) \cup (a_1, a_2) \cup \dots \cup (a_N, \ell), \\
 & \varphi(0, \lambda) = \varphi(\ell, \lambda) = 0, \quad \varphi(a_j^-, \lambda) = \varphi(a_j^+, \lambda), \\
 & -M_j \lambda^2 \varphi(a_j, \lambda) = \varphi'(a_j^+, \lambda) - \varphi'(a_j^-, \lambda),
 \end{aligned}$$

The (simple) eigenfrequencies λ_n of this problem are zeros of the generating function

$$F(\lambda) := \Phi(\ell, \lambda), \quad \Phi(0, \lambda) = 0, \quad \Phi'(0, \lambda) = 1.$$

They can be presented as a union of $N + 1$ separated series:

$$\{\lambda_n\}_{n=1}^{\infty} = \{\lambda_m^0\}_{m=1}^{\infty} \cup \left[\bigcup_{j=1}^N \{\lambda_m^j\}_{m=0}^{\infty} \right], \quad \lambda_m^j = \frac{\pi m}{a_{j+1} - a_j} + O\left(\frac{1}{m}\right).$$

Fourier Method

We present the solution of the IBVP in the form of the series

$$u(x, t) = \sum_{n=1}^{\infty} b_n(t) \phi_n(x), \quad u_t(x, t) = \sum_{n=1}^{\infty} \dot{b}_n(t) \phi_n(x).$$

Coefficients $b_n(t)$ can be found as

$$b_n(t) = \phi_n'(0) \int_0^t f(\tau) \frac{\sin \lambda_n(t - \tau)}{\lambda_n} d\tau,$$

$$\dot{b}_n(t) = \phi_n'(0) \int_0^t f(\tau) \cos \lambda_n(t - \tau) d\tau.$$

These equalities can be conveniently written in the form

$$c_n^{\pm}(t) = \int_0^t f(\tau) e^{\pm i\lambda_n \tau} d\tau, \quad c_n^{\pm}(t) := \left(\mp \frac{i\lambda_n}{\phi_n'(0)} b_n(t) + \frac{\dot{b}_n(t)}{\phi_n'(0)} \right) e^{i\lambda_n t}.$$

We use the spectral representation to create a scale of spaces \mathcal{H}_p (for $p > 0$, $\mathcal{H}_p = D(A^{p/2})$):

$$\mathcal{H}_p = \left\{ \varphi(x) = \sum_{n=1}^{\infty} \alpha_n \phi_n(x) : \|\varphi\|_p^2 = \sum_{n=1}^{\infty} |\alpha_n|^2 |n|^{2p} < \infty \right\}, \quad p \in \mathbb{R}.$$

So, for example,

$$\|u(\cdot, t)\|_{L^2(0, \ell)}^2 \asymp \sum_{n=1}^{\infty} |b_n(t)|^2, \quad \|u_t(\cdot, t)\|_{H^{-1}(0, \ell)}^2 \asymp \sum_{n=1}^{\infty} |\dot{b}_n(t)|^2.$$

For a regular string, $|\lambda_n| \asymp n$, $|\phi'_n(0)| \asymp n$, and so

$$\|u(\cdot, t)\|_{L^2(0, \ell)}^2 + \|u_t(\cdot, t)\|_{H^{-1}(0, \ell)}^2 \asymp \sum_{n=1}^{\infty} |c_n^\pm(t)|^2.$$

The Moment Problem

Exact controllability of our system in $L^2(0, \ell) \times H^{-1}(0, \ell)$ in the time interval $[0, T]$ is equivalent to solvability of the following moment problem in $L^2(0, T)$ for all $\{c_n^\pm\} \in \ell^2$:

$$c_n^\pm = \int_0^T f(t) e^{\pm i\lambda_n t} d\tau, \quad n \in \mathbb{N}.$$

The latter is in turn equivalent to the fact that the family $\{\exp(\pm i\lambda_n t)\}$ is a Riesz sequence in $L^2(0, T)$.

This is true (for a regular string) iff $T \geq 2\ell$.

The sharp regularity result is also follows from the Riesz sequence property.

Exponential Divided Differences (EDD)

For strings with attached masses:

(i) it is not clear how express non-symmetric spaces W_0 and W_1 in terms of the coefficients α_n ;

(ii) the relation $|\phi'_n(0)| \asymp n$ is not generally true;

(iii) for no T the family $\{\exp(\pm i\lambda_n t)\}$ can be a Riesz sequence in $L^2(0, T)$ because the sequence $\{\lambda_n\}$ is not separated:

$$\inf_{n \neq k} |\lambda_n - \lambda_k| = 0.$$

Assume $\{\mu_j\}$ is a non-repeating sequence. The exponential divided difference (EDD) of order zero for $\{e^{i\mu_n t}\}$ is

$[e^{i\mu_1 t}](t) := e^{i\mu_1 t}$. The EDD of order $n - 1$ is given by

$$[e^{i\mu_1 t}, \dots, e^{i\mu_n t}] = \frac{[e^{i\mu_1 t}, \dots, e^{i\mu_{n-1} t}] - [e^{i\mu_2 t}, \dots, e^{i\mu_n t}]}{\mu_1 - \mu_n}, \mu_1 \neq \mu_n.$$

One then easily derives the formulas

$$[e^{i\mu_1 t}, e^{i\mu_2 t}] = \frac{e^{i\mu_1 t} - e^{i\mu_2 t}}{\mu_1 - \mu_2}, \quad [e^{i\mu_1 t}, \dots, e^{i\mu_n t}] = \sum_{k=1}^n \frac{e^{i\mu_k t}}{\prod_{j \neq k} (\mu_k - \mu_j)}.$$

Bases of Exponential Divided Differences

The Riesz basis theory of exponential divided differences was developed in (Avdonin and Ivanov, 2001; Avdonin and Moran, 2001).

The generating function of the sequence $\{\pm\lambda_n\}$ is an entire function

$$F(\lambda) = \prod_{n \in \mathbb{N}} \left(1 - \frac{\lambda^2}{\lambda_n^2}\right)$$

of the exponential type of ℓ in \mathbb{C}_\pm . For some $h \in \mathbb{R}$,

$$|F(x + ih)| \asymp |x + ih|^{N-1}.$$

Therefore, the corresponding family of EDD $\mathcal{E} = \bigcup_{p \in \pm\mathbb{N}} \mathcal{E}_p$ forms a Riesz basis in the closure of its linear span in $L^2(0, T)$ for $T > 2\ell$.

The original moment problem

$$c_n^\pm = \int_0^T f(t) e^{\pm i\lambda_n t} d\tau, \quad n \in \mathbb{N},$$

can be rewritten in the form

$$\hat{c}_n^\pm = \int_0^T f(t) e_n^\pm(t) d\tau, \quad n \in \mathbb{N},$$

where $\mathcal{E} = \{e_n^\pm(t)\}$ is the corresponding family of EDD. Similarly, the relations

$$\alpha_n = \int_0^T f(t) \sin(\lambda_n t) d\tau, \quad n \in \mathbb{N},$$

can be rewritten in the form

$$\beta_n = \int_0^T f(t) s_n(t) d\tau, \quad n \in \mathbb{N},$$

Shape Controllability

Since \mathcal{E} forms a Riesz sequence in $L^2(0, T)$ for $T > 2\ell$, the family $S = \{s_n\}$ of the corresponding DD of sine functions forms a Riesz sequence in $L^2(0, T)$ for $T > \ell$.

Now we rewrite the relation $y(x, T) = \sum \alpha_n \phi_n(x)$ in the form $y(x, T) = \sum \beta_n \psi_n(x)$, where ψ_n are the corresponding linear combinations of ϕ_n .

Theorem 2 (Shape controllability). Let $T > \ell$, $y \in W_0$. There exists

$$f \in L^2(0, T), \quad \|f\|_{L^2(0, T)}^2 \asymp \|y\|_{W_0}^2,$$

such that

$$u^f(x, T) = y(x), \quad x \in \Omega.$$

This theorem implies that $\{\psi_n\}$ forms a Riesz basis in W_0 . From that we can derive the full controllability (Theorem 1).

Response operator

$$R^T : L^2(0, T) \mapsto L^2(0, T), \quad \text{Dom}(R^T) = \{f \in H^1(0, T), f(0) = 0\},$$

$$(R^T f)(t) = u_x^f(0, t), \quad t \in (0, T).$$

Theorem 2. Let $T > 2l$. Given R^T , one can find $\rho(x)$, a_j , M_j , l .

Step 1. From R^T , $T > 2a_1$, we find $\rho(x)$, $x \in [0, a_1]$; a_1 , M_1 .

Step 2. Leaf-peeling method. Let $T > 2l$. From R^T , we find the response operator of the reduced system defined on the interval $x > a_1$.

$$-M_j \lambda^2 \varphi(a_j, \lambda) = \varphi'(a_j^+, \lambda) - \varphi'(a_j^-, \lambda),$$

$$\tilde{m}(\lambda) = \frac{\varphi'(a_j^-, \lambda)}{\varphi(a_j, \lambda)} - M_j \lambda^2.$$

Our approach is based on the boundary control (BC) method.